

UDK 681.326.06:519.876.5

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In this paper we describe a simulation packet that enables the verification of the software portion of the controller before implementating the controller on a real object. This program is unique of its kind, as far as we know, because it enables the examination of the controller's behavior in planner's workplace and so considerably reduces start expenses. The simulation packet enables controlled execution of the user's program, clearly arranged writing out of data on the screen or on the printer and gives a chance for data modification.

**SIMULACIJSKI PRISTOP PRED UPORABO INDUSTRIJSKEGA
MIKRORAČUNALNIŠKEGA KRMILNIKA.**

V članku opisani simulacijski paket omogoča verifikacijo programskega dela krmilja pred vgraditvijo krmilnika na objekt. Po nam znanih podatkih je to edini tovrstni program, ki omogoča preizkus obnašanja krmilja na projektantovem delovnem mestu in s tem znatno znižanje zagonskih stroškov objekta. Simulacijski paket omogoča prikaz izvajanja uporabniškega programa, urejen in pregleden izpis vrednosti na zaslon ali na tiskalnik in možnost spreminjanja vrednosti podatkov.

1 Initial considerations about the industrial microcomputer controller and it's simulation

Requests for a system which upgrades standard programmable controller functions came from industry. Initial efforts were made by Metalna, Maribor. After it's definition phase the project was supported by the Research Society of Slovenia (Raziskovalna Skupnost Slovenije).

Intention and practical use of the industrial microcomputer controller

The controller is intended for control in capital equipment facilities plants, where heavy environment conditions and the immense equipment costs do not allow any compromise. A number of unique functions were built in the controller to obtain the required functionality. Special attention was dedicated to the user's program - control application development and verification tools.

The paper describes a unique part of the user development and verification software which allows controlled application verification at the planner's workplace. This function reduces starting expenses when a capital object is put into work.

With convenient tools, software design methods and simulation, most of the mistakes, bugs and imperfections of the controller's software are discovered and removed before implementation on an object.

Thus, the simulation of the controller's software can be carried out in different ways. Module simulation is specially efficient. It allows that only verified software blocks are put together into larger structures. Typical software modules are functions and subroutines like structures in high level language, and assembler like macros.

Simple use of the simulation packet is assured with it's hierarchical tree structured menu. The user selects from the menu on the screen the actions to be executed. Each action is determined with a function key on the keyboard. The user selects the desired action by pressing the adequate function key on the keyboard. Figure 1 shows an example of this principle.

METALNA Maribor
INDUSTRIAL CONTROLLER
SIMULATION

| | |
|------------------|-------------------------|
| F1 SIMULATION | F8 END OF SIMULATION |
|------------------|-------------------------|

Fig. 1: The initial simulation menu.

After selecting the adequate menu's window of a selected action, it lights up in yellow colour. This light is an advertisement for the user to notice which action he had selected. In the same way, the simulator advertises the user

when he returns back over the menus. If there is no special, objective reasons, the selected action is executed immediately.

The user can present his program for the controller either in a graphic form, the so-called contact networks, or in textual, mnemonic form.

The user must call the analyser before applying the simulation of his program. The analyser is a kind of compiler. It was designed for this special purpose: it translates the user's program together with the declaration module and possibly with some other files for functions or subroutines into the 'object form' which is 'understood' and executed by the simulation, when requested.

The simulation can be executed only when the analyser does not find and report any error(s) in the user's program file, nor in the declaration module's file. An example of both files is on Figure 2a and Figure 2b.

```

MAIN
SET M1
RESET M2
BP 5
ADD CB12, CB328, B1
SUB CW7, CW8, W16
MUL CL323, CL818, L234
W17 = CW17
DIV CW111, CW71, W12(W17), W20
BP 9
AND W16, W17, W19
CPL CB12, B12
NEG CB12, B13
BP 10
RLC CL328, 65, L235
SLC CB115, 5, B235
TRANS CB115.3, 3, L236.7
TRANS M300, 100, M250
Q = M1
JPQ 33
NOP
33 L237 = L236
M21 = N ( (M1 A M2) O (W16 LT CW87) )
BP 20
NOP
BP 25
END.

```

Fig. 2a: The user's program (file TEST.MPR)

```

DECLAR
CONST
CB10 <- 10
CB12 <- 12
CB115 <- 115
CB119 <- 119
CB123 <- 123
CB321 <- 30
CB328 <- 32
CB378 <- 37
CW17 <- 17
CW71 <- 71
CW73 <- 7300
CW78 <- 78
CW87 <- 87
CW111 <- 111
CW200 <- 2000
CW312 <- 312
CW419 <- 8841
CW788 <- 788
CLO <- 0
CL5 <- 5
CL46 <- 46
CL49 <- 49
CL64 <- 64
CL175 <- 175
CL200 <- 2000000

```

```

CL215 <- 215
CL287 <- 287
CL300 <- 3000000
CL328 <- 328000
CL818 <- 818000000
ENDCONST
IOSPEC
MOD1 is TY31
MOD2 is TY31
MOD3 is TY31
MOD4 is TY31
BLOCK
CS 11, YES, 70
C 11, M6, M7, M8, M61, M62, M63, M64
CS 12, NO, 80
C 12, M6, M7, M8, M9, M10, M11, M12
CS 13, YES, 90
C 13, M10, M11, M5, M6, M16, M17, M88
TS 12, 10ms, YES, 999
T 12, M2, M29, M3, -
TS 11, 100ms, NO, 50
T 11, M1, M2, M3, M4
TS 13, 1ms, NO, 100
T 13, M3, M4, M2, M1
TXS 23, READ, 2, "START"
TX 23, M22, M3
TXS 24, WRITE, 2, "O.K."
TX 24, M21, M3
TXS 25, NUMWRITE, 2, B333
TX 25, M20, M3
TXS 26, NUMREAD, 2, L338
TX 26, M26, M3
MS 13, 100ms, NO, 333
M 13, M2, M20
MS 14, 10ms, YES, 238
M 14, M3, M27
MS 15, 100ms, NO, 669
M 15, M27, M84
DS 8, 1s, 11, 8, B
D 8, M2, M32, M33
DS 16, 1s, 18, 16, W
D 16, M25, M26, M37
DS 32, 1s, 13, 32, L
D 32, M2, M21, M30
RS 16, FIFO, 22, L
R 16, M2, M24, M32, M41, M52
RS 17, LIFO, 30, B
R 17, M2, M25, M35, M43, M53
RS 18, FIFO, 20, W
R 18, M3, M55, M55, M53, M57
ENDBLOCK
ENDIO
END.

```

Fig. 2b: The declaration module (file D2.DCM)

NOTE

The user does not need to write the file type (MPR for user's (or main) program or DCM for declaration module), because special purpose editors do this. File types are always hidden from the users!

Enter main program's name : TEST_....

Fig. 3a: Reading a name of the main program.

After all necessary files were translated, the simulation establishes the presence of error(s) very simply. If the analyser finds any error(s), then it does not produce the object file, which is a direct input to the simulation. In case of an error the simulator writes a message on the screen. In this message it tells the user that he can not execute the simulation because the error(s)

is(are) found and that the user can correct the error(s) in a corresponding editor.

The program **SIMULATION** first of all reads the name of user program's file (or main program's file) and the name of the declaration module. Figures 3a and 3b show the user's answers to both questions.

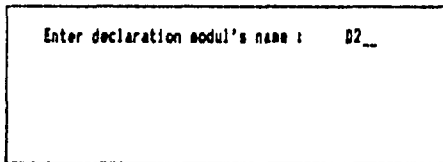


Fig. 3b: Reading the name of the declaration module.

After successful return from the analyser and before the simulation execution, the simulator writes a detailed report about constants and function blocks used in the declaration module (Figures 4a and 4b).

| C O N S T A N T S | | | | | |
|-------------------|-----------|-------|------|-------|---------|
| CB10 | 10 | CB12 | 12 | CB15 | 15 |
| CB19 | 19 | CB21 | 21 | CB23 | 23 |
| CB28 | 28 | CB27 | 27 | CB28 | 28 |
| CB7 | 7 | CB73 | 7300 | CB78 | 78 |
| CB12 | 312 | CB11 | 11 | CB200 | 2000 |
| CL5 | 5 | CL49 | 49 | CL6 | 6 |
| CL84 | 84 | CL175 | 175 | CL200 | 2000000 |
| CL215 | 215 | CL287 | 287 | CL328 | 328000 |
| CLB18 | 818000000 | | | | |

Fig. 4a: The report about CONSTANTS.

If the value of a constant is too large for it's data type, then the simulator assigns the largest positive or negative value to that constant, depended on its sign! The data type of a constant is appointed by the second letter of the constant's name: B, W or L for byte (8 bits), word (16 bits) or a longword (32 bits).

The data type of an instruction operand identifies how many bits of storage should be considered as a unit and what is the interpretation of that unit to be. The simulator only recognises the integer, BCD and ASCII data. An integer can be stored in a bit, byte, word or in longword. Some instructions interpret the integer data as a signed value, while others as a bit strings.

| F U N C T I O N B L O C K S | | | | | |
|-----------------------------|------|------------|------|------------|------|
| COUNTER | C11 | COUNTER | C12 | COUNTER | C13 |
| TIMER | T124 | TEST | T125 | TEST | T126 |
| MONOSTABLE | M13 | MONOSTABLE | M14 | MONOSTABLE | M15 |
| REGISTER | R16 | REGISTER | R17 | REGISTER | R18 |

Fig. 4b: The report about FUNCTION BLOCKS.

1.1 Representation of a types of data and function blocks

The user can use the following types of data:

(a) **CONSTANTS**

The user assigns initial values to constants in the declaration module. During the execution of the simulation the simulator has read only access to it's value. The user can assign a new value to a constant in the later described menus **SINGLE CHANGE** and **ADJUST EDITOR**.

(b) **SYSTEM DATA**

The controller's system data are set up by the operating system. The simulator simulates this function by

assigning them values. It can read only system data. The same principle to modify the system data is in valid as for constants.

(c) **INTERNAL DATA**

Internal data are general purpose data. The simulator can use them similarly as variables in a high level language: their values can be modified by the simulator.

(d) **INPUT DATA**

Input data are external physical inputs into the controller.

(e) **OUTPUT DATA**

Output data are physical outputs out from the controller.

We use 'the single assignment rule' for all types of data, because of the simulation of parallel execution mutually exclusive events.

Overview of the controller's data types

The user can use almost all combinations of types of data with data types in simulation. This survey is shown on Figure 5.

| TYPE OF DATA | TYPE's DATA NAME | TYPE's DATA MARK | DATA TYPE's NAME | DATA TYPE's MARK | A SAMPLE |
|-----------------------|------------------|------------------|------------------|------------------|----------|
| CONSTANT DATA: | | | | | |
| BYTE | Constant C | Byte | B | | CB18 |
| WORD | Constant C | Word | W | | CW555 |
| LONGWORD | Constant C | Longword | L | | CL234 |
| SYSTEM DATA: | | | | | |
| BIT | System | S | Bit | * | S12 |
| BYTE | System | S | Byte | B | SB373 |
| WORD | System | S | Word | W | SW383 |
| LONGWORD | System | S | Longword | L | SL947 |
| INTERNAL DATA: | | | | | |
| BIT | Internal | * | Bit | M | M991 |
| BYTE | Internal | * | Byte | B | B3 |
| WORD | Internal | * | Word | W | W495 |
| LONGWORD | Internal | * | Longword | L | L952 |
| OUTPUT DATA: | | | | | |
| BIT | Output | O | Bit | * | O12.13 |
| BYTE | Output | O | Byte | B | OB10.4 |
| WORD | Output | O | Word | W | OW4.10 |
| LONGWORD | Output | O | Longword | L | OL2.2 |
| INPUT DATA: | | | | | |
| BIT | Input | I | Bit | * | I5.13 |
| BYTE | Input | I | Byte | B | IB8.10 |
| WORD | Input | I | Word | W | IW10.0 |
| LONGWORD | Input | I | Longword | L | IL1.3 |

NOTE

Asterisk "*" means that at this place there is no mark!

Fig. 5: Survey about types of data.

The user has six types of function blocks besides the types of data mentioned above. The function blocks are:

(a) **TIMER**

The timer enables temporal control over events in an object. After a certain time delay something can happen, the value of which is programmable.

(b) **MONOSTABLE**

The monostable enables temporal control, too. It generates a pulse of specific duration, the value of which is programmable.

The main difference between the monostable and the timer is the following: the user can programmably control the timer through its inputs. After the user had enabled the monostable to start running, he can no longer programmably influence the monostable. Only one exception is allowed: the user can repeatedly start the monostable from the beginning!

(c) **COUNTER**

The counter permits the upcounting and downcounting of events. These two operations can be performed simultaneously or not, as required.

(d) **DRUM CONTROLLER**

The drum controller enables temporal or event-driven (through its inputs) control: values of output bits of current drum step are assigned to actual bits. The two mentioned modes of operation are mutually exclusive.

(e) **REGISTER**

The register enables storage of data in two different ways:

- * FIFO stack or
- * LIFO queue.

(f) **TEXT**

The text enables simple input/output operations (communication between the user and the controller).

1.2 Simulation of a user's program execution

The simulation receives the user's program merged together with other files in object code on a file. The file has sequential organization. It consists of records arranged in the sequence in which they are written in the file (the first record written is the first record in the file, ... and so on).

Particular instruction needs more records. Records of the same instruction are always arranged in this way: a first record contains an operand which will have a result (one or two for division), a following record is a second operand, if it indeed exists in syntax of an instruction. After operands, if the instruction has any, comes the operator. This is an instruction which will be executed.

The simulator reads the records in the described regular sequence, too. Simulation of execution is based on the principle of **stack computer**. The simulator reads a record from the object code's file. Records are already in correct sequence, in so-called **reverse Polish notation**. The content of a record is either **an operator** or **an operand**.

If it is an operand then the simulator pushes it on the stack.

If it is an operator then the simulator pulls the corresponding number of operands from the stack, executes the operator (instruction) and assigns a value to a result.

The IMCL (Industrial Microcomputer Controller Language) is a **mnemonic programmable language** for our controller. The user can simulate all of the instructions of the IMCL:

ARITHMETIC OPERATIONS:

- (1) ADD - arithmetic addition
- (2) SUB - arithmetic subtraction
- (3) DIV - arithmetic division

Divide by zero:

The simulator assigns the largest positive or negative value to the result, dependently on the numerator sign, a zero to the remainder and reports the overflow of the result.

The simulator writes the values of condition flags (Negative, Zero, overflow and Carry) on the screen, then follow the messages about the mode of execution and about the current number of cycles - reiterations of execution of the user's program.

In case of dividing by zero the simulator always breaks execution and writes a message. After the message the user can continue with the execution of his program. He must press the key RUN - Figure 6!

- (4) MUL - arithmetic multiplication

BIT OPERATIONS:

- (5) A - logical AND operation over a bit's expressions
- (6) O - logical OR operation over a bit's expressions
- (7) N - negation of a bit's expression
- (8) SET - bit set
- (9) RESET - reset bit
- (10) P - protection and assignment

BIT OPERATIONS BETWEEN TERMS

(8, 16 or 32 bit string's length):

- (11) OR - logical OR operation
- (12) XOR - logical XOR operation
- (13) AND - logical AND operation
- (14) NAND - logical NAND operation
- (15) NOR - logical NOR operation

COMPLEMENTS:

- (16) NEG - one's complement
- (17) CPL - two's complement

TRANSFER OF BIT STRING:

- (18) SLC - shift left
- (19) SRC - shift right
- (20) RLC - rotate left
- (21) RRC - rotate right
- (22) TRANS - general purpose transfer of bits between bit strings

RELATIONAL OPERATORS:

- (23) NE - operands are not equal ?
- (24) EQ - are both operands equal ?
- (25) LT - first operand is less than second one
- (26) LTE - first operand is less than or equals to the second one
- (27) GT - first operand is greater than second one
- (28) GTE - first operand is greater than or equals to the second one

CONVERSIONS:

- (29) CBIN - conversion from BCD to two's complement
- (30) CBCD - conversion from two's complement to BCD

CONTROL OPERATIONS:

- (31) JPQ - jump if Q bit is equal 1
- (32) JPnotQ - jump if Q bit is equal 0
- (33) JPX - jump if X bit is equal 1

- (34) JFnotX - jump if X bit is equal 0
 - (35) JP - unconditional Jump
- The simulator writes a message to the user that the next step will be to execute a labelled program statement corresponding to the label of the JUMP statement. Jump skips the statements between JUMP instruction and this statement!
- The simulator writes this message only in step-wise mode of execution!

CALL OPERATIONS:

- (36) CALLM - calling a module
- (37) CALLQ - conditional calling a module

MISCELLANEOUS OPERATIONS:

- (38) BP - break point
- When the simulator reaches a break point that it is not cancelled out in the user's program, it breaks te execution of simulation. The simulator writes a message about the break point irrespective of the mode of execution: step-wise mode or continous mode.
- (39) EQUAL - assignement an operand's value to a result
 - (40) NOP - no operation
- In the step-wise mode of execution the simulator writes only a message that it reached the NOP instruction and reassigns all condition flags to zero.

Instructions are orthogonal which means that the user can use the same instruction with different data types. For example: once with a byte, some other time with a longword.

Internal types of data, which are longer than one bit, we can address also in index mode and indirect (deferred mode); for example: ADD (W3), W4(W6), W3. In such cases the value of indirectly addressed internal variable tells the simulator on which internal datum (variable) the instruction will be actually executed, or in index mode of addressing, (indexed variable is within round brackets) a sum of both internal variables' values gives index (address) of actual internal datum.

1.3 Representation of a user's program execution

You can repeatedly execute the simulation of yours program as many times as you like. Every time you can choose one mode from the following modes of execution:

- (a) more cycles,
- (b) single cycle,
- (c) step-wise mode,
- (d) continous mode,
- (e) with break point(s) or
- (f) without break point(s).

Some modes of execution are compatible with others. The user can, for example, execute the simulation in step-wise mode, with break points and has more cycles. One cycle is one iteration of the user's program execution.

The key RUN (Figure 6) enables a commencement or a continuation of user's program execution.

The step-wise mode of execution enables the user's program execution step by step, one instruction after another. For particular instructions a message is written on the screen. The message contains rudimentary informations: which instruction is executed,

operand names and values and values of conditional flags (Negative, Zero, oVerflow and Carry).

The simulation can start with the following default modes of execution: a single cycle, continous mode and with break points! If the user does not choose the step-wise mode then the entire user's program is executed at least once (depended on the number of cycles - iterations of execution!) without the simulator writing out any message, except if there is a run time error or a break point instruction or a jump instruction!

```
STEP WISE      : No
Number of cycles : 1
Execution time  : 300 ns (of one cycle !)
```

Top of the file !

The program is READY for execution !

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

| | | | | | | | |
|-----------|---------------------|--------------------|----------------------|--------------------|-------------------|----------------------|------------|
| F1 RUN | F2 FROM BEGIN | F3 STEP WISE | F4 MORE CYCLES | F5 POWER OFF | F6 ADJ MODE | F7 BREAK POINT | F8 EXIT |
|-----------|---------------------|--------------------|----------------------|--------------------|-------------------|----------------------|------------|

Fig. 6: A fundamental menu of simulation.

The user selects either the step-wise mode or the oposite continous mode, with the key **STEP WISE** (Figure 6). The step-wise mode and the continous mode are mutually exclusive. A new state is oposite to a previous state. At commencement of execution the default state is the continous mode, so if the user wishes the step-wise mode, he must press the key **STEP WISE** (Figure 6).

The key **MORE CYCLES** permits to inscribe the value of the number of cycles (Figure 7).

```
Number of cycles : 5....
It must be positive and less than 32001 !
```

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

| | | | | | | | |
|-----------|---------------------|--------------------|----------------------|--------------------|-------------------|----------------------|------------|
| F1 RUN | F2 FROM BEGIN | F3 STEP WISE | F4 MORE CYCLES | F5 POWER OFF | F6 ADJ MODE | F7 BREAK POINT | F8 EXIT |
|-----------|---------------------|--------------------|----------------------|--------------------|-------------------|----------------------|------------|

Fig. 7: The user inscribes the value of the number of cycles.

The user can cancel out all of the used **break points** or just some of them, or gives them active status, if he chooses a menu of break points (the key **BREAK POINT**), which is shown on Figure 8.

```
BREAK - POINTS
BP5  BP9  BP10 BP20 BP25
```

```
COLOR means :
Break-point is NOT CANCELED ! Break-point is CANCELED !
```

| | | | | |
|---------------------|------------------|---------------------|------------------|------------|
| F1 CANCEL ALL | F2 SET ALL | F3 CANCEL ONE | F4 SET ONE | F8 EXIT |
|---------------------|------------------|---------------------|------------------|------------|

Fig. 8: A menu of break points.

If break point (BP) is cancelled out, then the execution of simulation is not broken!

Before executing an instruction, the simulator verifies if the necessary operands have values. If they do not have, the simulator calls the user's attention to this fact. The user can choose either to inscribe an initial value to a datum or to confirm a simulation's proposal to assign a zero value to that datum.

The simulation enables all inscriptions of digits (numerical data) in:

- (a) binary number system,
- (b) octal number system,
- (c) decimal number system and
- (d) hexadecimal number system.

The user indicates the desired number system by inscribing the first character: B, O or H for binary, octal or hexadecimal number system. For decimal number system he does not inscribe any letter before digits!

During the inscription of an integer number, the simulator ignores the prohibited characters. For example: letters that do not have sense for the selected number system, or letters the values of which are larger than the basis of the number system decremented by one. Likewise, the simulator reports an error if the numerical value exceeds the allowed integer interval of datum's data type (a bit, a byte, a word or a longword).

During execution (depending on the selected modes of execution and menus) the user can make hard-copy of the screen, use ADJUST MODE that permits an overview and adjustment of used data and function blocks, select different modes of execution, cancel out or not cancel out break point(s) and, if he wishes, he can terminate the simulation. This function is enabled by the key EXIT, that always brings us into the previous menu.

The simulation permits the user to repeatedly execute different user's programs or combinations of the same user's program with different declaration modules.

2 An instance of step-wise execution of a simple user's program

Figure 9 shows an example of step-wise execution of a simple user's program, the source mnemonic form of which was presented on Figure 2a. We cut off the fundamental menu (presented on Figure 6) in order to spare space. Each message is written above this menu. Temporal order of messages is from top to the bottom of a paper.

```

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 0 0 0
Execution time  : 500 ns (of one cycle !!)
Instruction : SET

Result(s) : M1 : 1
  
```

```

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 1 0 0
Execution time  : 500 ns (of one cycle !!)
Instruction : RESET

Result(s) : M2 : 0

The execution of the program is broken at BP5 !

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 0 0 0
Execution time  : 500 ns (of one cycle !!)
Instruction : ADD

Operand(s) : CB12 : 12
             CB328 : 32
Result(s) : B1 : 44

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 0 0 0
Execution time  : 500 ns (of one cycle !!)
Instruction : SUB

Operand(s) : CM7 : 19473
             CM8 : 8214
Result(s) : M16 : 11259

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 0 1 0
Execution time  : 500 ns (of one cycle !!)
Instruction : MUL

Operand(s) : CL323 : 9591575
             CL818 : 81800000
Result(s) : L234 : 2147483647

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 0 0 0
Execution time  : 500 ns (of one cycle !!)
Instruction : =

Operand(s) : CM17

Result(s) : M17 : 17

STEP WISE      : Yes           Flags : N Z V C
Number of cycles : 5           0 0 0 0
Execution time  : 500 ns (of one cycle !!)
Instruction : DIV

Operand(s) : CM11 : 111
             CM71 : 71
Result(s) : M12(M17) : 1 (---> M61)
             M20 : 40 (remainder)
  
```

The execution of the program is broken at BP9 !

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : AND

Operand(s) :
W16 : 00101011 11111011
W17 : 00000000 00010001

Result(s) :
W19 : 00000000 00010001
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      1  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : CPL

Operand(s) :
CB12 : 00001100

Result(s) :
B12 : 11110100
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      1  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : NEG

Operand(s) :
CB12 : 00001100

Result(s) :
B13 : 11110011
    
```

The execution of the program is broken at BP10 !

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  1  0
Execution time  : 500 ns (of one cycle !)

Instruction : RLC

Operand(s) :
CL12B : 00000000 00000101 00000001 01000000
Rotate no. : 65 ( => 1 !!! )

Result(s) :
L235 : 00000000 00001010 00000010 10000000
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : SLC

Operand(s) :
CB115 : 01110011
Shift no. : 5

Result(s) :
B235 : 01100000
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : TRANS

Operand(s) :
CB115 : 01110011
No. of bits : 3

Result(s) :
L236 : 00000010 00010101 01000111 00111011
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : TRANS

Operand(s) :
M300 : 00000000 00000000 00000000 00000000 ...
No. of bits : 100

Result(s) :
M250 : 00000000 00000000 00000000 00000000 ...
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : =

Operand(s) :
R1

Result(s) :
D : 1
    
```

The execution of the program is broken at LABEL J3 !

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  0  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : =

Operand(s) :
L236

Result(s) :
L237 : 3494B923
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  1  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : A

Operand(s) :
M2 : 0
R1 : 1

Result(s) :
Result is : 0
    
```

```

STEP WISE      : Yes                      Flags :  N  Z  V  C
Number of cycles : 5                      0  1  0  0
Execution time  : 500 ns (of one cycle !)

Instruction : LT

Operand(s) :
W16 : 11259
CB87 : 87

Result(s) :
Result is : 0
    
```

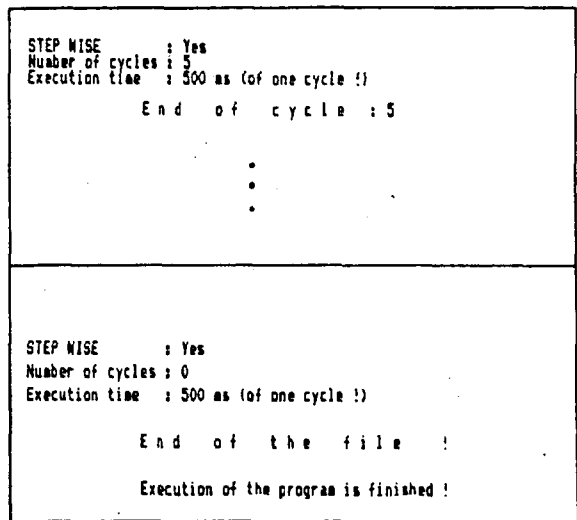
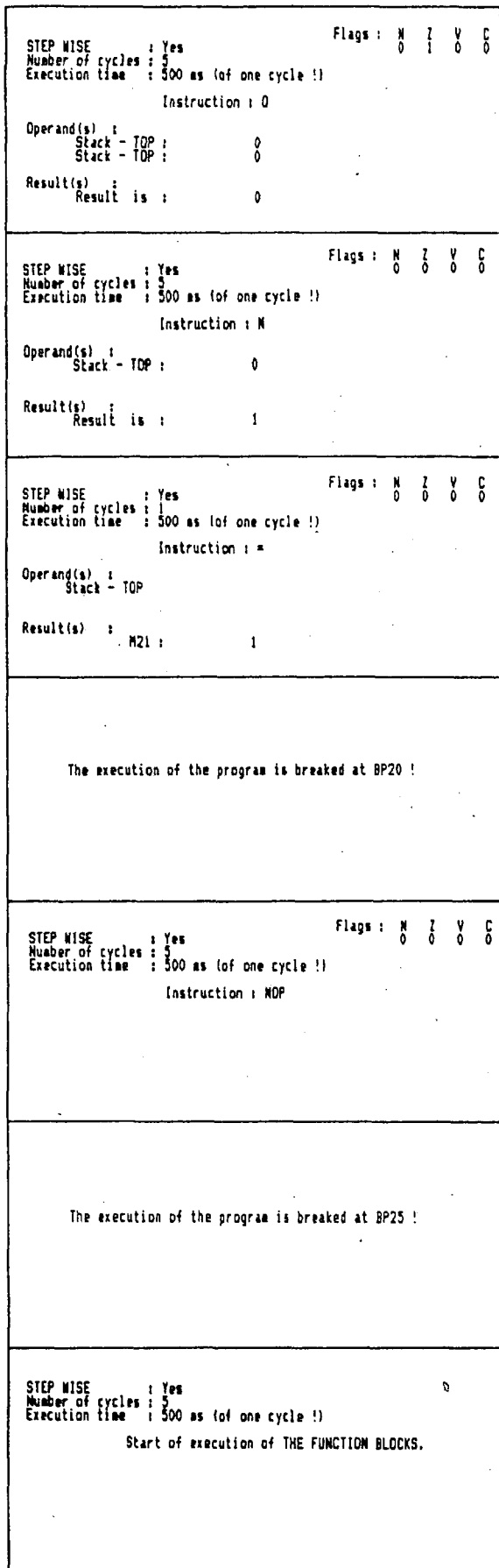


Fig. 9: A step-wise mode of execution of a simple user's program.

3 Adjustment and writing out values

In the fundamental simulation menu (Figure 6), the user must select ADJUST MODE (Figure 10). The simulator permits two modes of adjusting and writing out data.

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

| | | | | | | |
|--------------------|-------------------|----------------------|--------------------|---------------------|------------------------|------------|
| F1 CONT VIEW | F2 PRG VIEW | F3 DRUM EDITOR | F4 PRINT ALL | F5 ADJ EDITOR | F6 SINGLE CHANGE | F8 EXIT |
|--------------------|-------------------|----------------------|--------------------|---------------------|------------------------|------------|

Fig. 10: A menu of ADJUST MODE.

The first mode is directed to a particular datum or function block and so we call it SINGLE CHANGE (Figure 11). The second mode is directed to all values of the same type of data - ADJUST EDITOR (Figure 12).

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

| | | | | | |
|-----------------------------|--------------------------------------|---------------------------------------|----------------------|----------------------|--------------------|
| F1 CONSTANT NONSTABLE | F2 SYSTEM VARIABLE REGISTER | F3 INTERNAL VARIABLE COUNTER | F4 INPUT TIMER | F5 OUTPUT DRUM | F8 EXIT TEXT |
|-----------------------------|--------------------------------------|---------------------------------------|----------------------|----------------------|--------------------|

Fig. 11: A menu of SINGLE CHANGE.

| | 0 | CWO 1 | 2 | Radix 3 | 4 | 5 | Constant Word 6 | 7 |
|----|---|--------|---|---------|---|---|-----------------|--------|
| 0 | - | - | - | - | - | - | - | 00002T |
| 1 | - | - | - | - | - | - | - | - |
| 2 | - | - | - | - | - | - | - | - |
| 3 | - | - | - | - | - | - | - | - |
| 4 | - | - | - | - | - | - | - | - |
| 5 | - | - | - | - | - | - | - | - |
| 6 | - | - | - | - | - | - | - | - |
| 7 | - | - | - | - | - | - | - | - |
| 8 | - | - | - | - | - | - | - | - |
| 9 | - | - | - | - | - | - | - | - |
| 10 | - | 000107 | - | 016204 | - | - | - | 000127 |
| 11 | - | - | - | - | - | - | - | - |
| 12 | - | 000157 | - | - | - | - | - | - |

You can use keys on the Numeric Keypad? Help: press <Alt> H

| | | | | | | | |
|-----------------------------|--------------------------|-----------------------------|-----------------------------|--------------------------|----------------------------|--------------------------------|----------------------|
| F1 FILE TOP BOTTOM | F2 PAGE UP DOWN | F3 PAGE LEFT RIGHT | F4 PAGE TOP BOTTOM | F5 LINE UP DOWN | F6 LINE BEGIN END | F7 CHANGE VALUE PRINT | F8 EXIT LINE ? |
|-----------------------------|--------------------------|-----------------------------|-----------------------------|--------------------------|----------------------------|--------------------------------|----------------------|

Fig. 12: A menu of ADJUST EDITOR.

The way of selection is identical for both modes, because it runs through similar menus. The user selection starts on menu of types of data (Figure 13a). There are constants, internal data, system data, input and output data. The user chooses between a bit, a byte, a word and a longword in the next menu of data types (Figure 13b). The user can choose all data types for any selected type of data except a bit for constants, because the simulator does not have a constant bit!

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !



Fig. 13a: Menu of types of data.

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

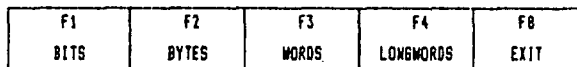
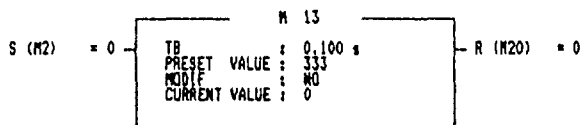


Fig. 13b: Menu of data types.

3.1 Adjustment and writing out values of function blocks' data

The menu SINGLE CHANGE (Figure 11) enables adjustment and writing out values of function blocks' data.

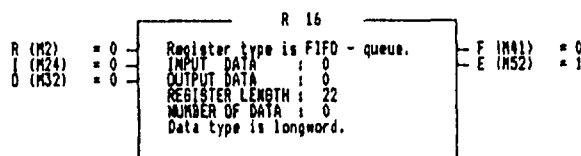
After selecting the type of a function block, the user inscribes its successive number and then, if it actually exists, the simulator draws its picture on the screen. The simulator then writes important information about it: type of function block, its successive number, names and values of its input and output bits and current values of its typical variables. In a menu, under each drawing, the user can read which variables he can adjust and what actions he can use (Figures 14a, 14b, 14c, 14d, 14e and 14f).



If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !



Fig. 14a: A menu of MONOSTABLE.



If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

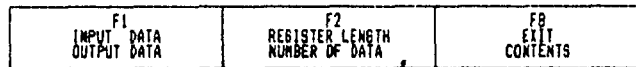
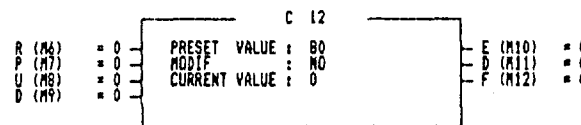


Fig. 14b: A menu of REGISTER.



If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

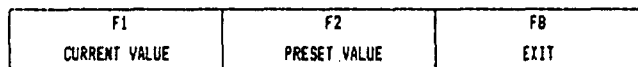
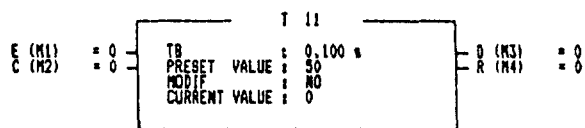


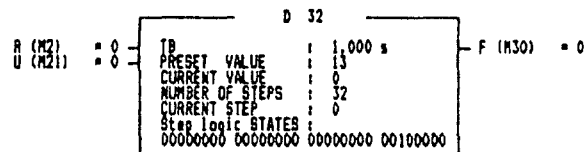
Fig. 14c: A menu of COUNTER.



If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !



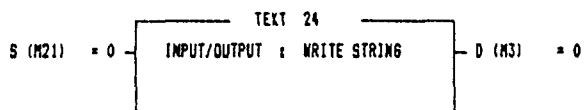
Fig. 14d: A menu of TIMER.



If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !



Fig. 14e: A menu of DRUM.



Your message is O.K. .

If you wish HARD COPY of the screen press <SHIFT> <PrtSc> !

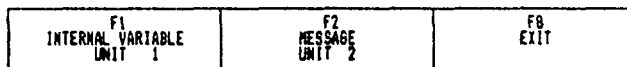


Fig. 14f: A menu of TEXT.

3.2 Adjustment and writing out values of data

As mentioned above, the user can adjust and write out values of data in two places in our simulation.

3.3 SINGLE CHANGE

After selecting type of data and its data type, the user inscribes its successive number in menu SINGLE CHANGE. If the entered name is correct in the context of Figure 5 and has a value, then the simulator writes out its value in binary, octal, decimal and hexadecimal number system. Now, the user can adjust the value or return to the menu of data types. An instance of choosing and adjusting of a datum CW200 in menu SINGLE CHANGE is shown on figures 15a and 15b.

Constant Word NUMBER : 200...

It must be greater than -1 and less than 1000 !

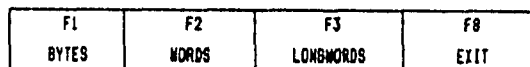


Fig. 15a: Choosing a datum.

CW200 -- Constant Word

```

OLD VALUE :          NEW VALUE :
Binary : 0000 0111 1101 0000   Binary : 1111 1000 0011 0000
Octal  : 003720                Octal  : 774060
Decimal: 2000                  Decimal: -2000
Hex    : 07D0                  Hex    : F830
    
```

Is new number's value correct ?
Answer with 'Y' or 'N' !

| | | | |
|-------|-------|-----------|------|
| F1 | F2 | F3 | F8 |
| BYTES | WORDS | LONGWORDS | EXIT |

Fig. 15b: Adjusting the same datum.

3.3.1 ADJUST EDITOR

ADJUST EDITOR is a screen editor that enables overlooking of all values of a selected type of data. We can not usually write all the values on a screen at the same time. We can see those values which are not momentary on the screen by moving the window through a table of values (we called it a file sometimes). Function keys of the menu of ADJUST EDITOR enable this moving (Figure 16).

```

(Home) . . . . . To left on line
(End) . . . . . To right on line
(PgUp) . . . . . Page up
(PgDn) . . . . . Page down
(Up Arrow) . . . . . Line up
(Down Arrow) . . . . . Line down
(Left Arrow) . . . . . Bit left
(Right Arrow) . . . . . Bit right
(CTRL) (Home) . . . . . To top of page
(CTRL) (End) . . . . . To bottom of page
(CTRL) (PgUp) . . . . . To top of file
(CTRL) (PgDn) . . . . . To bottom of file
(CTRL) (Left Arrow) . . . . . Word left
(CTRL) (Right Arrow) or (Tab) . . . . . Word right
    
```

You can use keys on the Numeric Keypad! Help: press <Alt> H

| | | | | | | | |
|-----------------------------|--------------------------|-----------------------------|-----------------------------|--------------------------|----------------------------|--------------------------------|----------------------|
| F1 FILE TOP BOTTOM | F2 PAGE UP DOWN | F3 PAGE LEFT RIGHT | F4 PAGE TOP BOTTOM | F5 LINE UP DOWN | F6 LINE BEGIN END | F7 CHANGE VALUE PRINT | F8 EXIT LINE ? |
|-----------------------------|--------------------------|-----------------------------|-----------------------------|--------------------------|----------------------------|--------------------------------|----------------------|

Fig. 16: The possibilities of ADJUST EDITOR.

We can move

- * to top of a file and
- * to bottom of a file.

We can move window

- * up,
- * down,
- * left and
- * right.

Within a window we can move

- * to top of a page and
- * to bottom of a page.

We can move a line

- * up and
- * down

and inside of the line

- * to left on line (beginning of line),
- * to right on line (end of line)

and from one datum to another

- * a datum left and
- * a datum right.

We can move out of a current window only by moving a window, because by moving within a window we can not come out of it.

Such moving is often time-consuming and as we wished to increase the efficiency of the ADJUST EDITOR, we added the above described possibilities still another one: the movement

to a datum required by the user (the key LINE ? on Figure 16).

Besides these, function keys, we can also use the keypad's keys for the same purpose.

The key CHANGE VALUE permits adjustment of values and the key PRINT enables writing out all values of the selected type of data, clearly arranged on the printer.

4 Conclusion

The presented simulation packet is written in the programming language Turbo Pascal. The user can execute it on all personal computers IBM XT/AT type, or compatible, equipped with an operating system MSDOS.

The simulation packet is a composition of twelve independent programs, which are connected with standard procedure Execute. The number of source program lines exceeds 50000, the object code is more than 360k bytes of length.

The SIMULATOR is an integral part of the user's development tools. Consequently, the entire project offers the special purpose environments to the users.

5 References:

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- * Programmable Contrölers SIMATIC S5 (different variants), SIMENS, 1984
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- * R.E Fairley, Software Engineering Concepts, McGraw-Hill Book Company, 1985
- * VAX Architecture Handbook, Digital Equipment Corporation, 1981