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Balanced Abelian group-valued functions on directed graphs

Yonah Cherniavsky * Department of Mathematics, Ariel University, Ariel, Israel

Avraham Goldstein

Borough of Manhattan Community College, CUNY, New York, USA

Vadim E. Levit

Department of Computer Science, Ariel University, Ariel, Israel

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Abstract

We discuss functions from the edges and vertices of a directed graph to an Abelian group. A function is called balanced if the sum of its values along any cycle is zero. The set of all balanced functions forms an Abelian group under addition. We study this group in two cases: when we are allowed to walk against the direction of an edge taking the opposite value of the function and when we are not allowed to walk against the direction.

Keywords: Consistent graphs, balanced signed graphs, balanced labelings of graphs, gain graphs, weighted graphs.

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1 Introduction

Let A be an Abelian group with the group operation denoted by + and the identity element denoted by 0. Let G be a graph. Roughly speaking, an A-valued function f on vertices and/or edges of G is called *balanced* if the sum of its values along any cycle of G is 0. Our cycles are not permitted to have repeating edges.

The study of balanced functions can be conducted in three cases:

^{*}Corresponding author

E-mail addresses: yonahch@ariel.ac.il (Yonah Cherniavsky), avraham.goldstein.nyc@gmail.com (Avraham Goldstein), levitv@ariel.ac.il (Vadim E. Levit)

- 1. The graph G is directed with the set of vertices V and the set of directed edges E. When traveling between the vertices, we are allowed to travel with or against the direction of the edges. The value of a function f on \bar{e} , which represents traveling the edge e against its direction, is equal to -f(e). In this context, when the function is defined on edges only, the pair (G, f) is called a network or a directed network. In this paper we shall call this *the flexible case*, meaning that the direction of an edge does not forbid us to walk against it. The notion of balanced functions on edges for the flexible case, for functions taking values only on the edges, is introduced in the literature under different names. Thus, for example, in [1] the set of such functions is exactly Im(d), where d is the "exterior differential", which maps a function f defined on vertices to the function df on edges defined by the equality $(df)(e) = f(e_+) - f(e_+)$ $f(e_{-})$, where e_{-} and e_{+} are the origin and the end of a directed edge e. In [11], in somewhat different language, that set is referred to as the set of consistent graphs. In [13] such functions have been introduced under the name "color-coboundaries". They also appear in literature under the name "tensions". They have been extensively studied, recent examples include [3, 4, 6, 10, 14]. In [5] balanced functions on edges appear in a certain connection with geometric representations of the Coxeter group associated to a graph. In a rather common terminology introduced by Zaslavsky, [15], a pair of a graph and such a function on the edges of a graph is called a "gain graph".
- 2. The graph G is directed with the set of vertices V and the set of directed edges E, but we are only allowed to travel with the direction of the edges. In this paper we shall call this *the rigid case*. When f takes values only on the edges then in some literature, following Serre, [12], the flexible case is described as a particular instance of the rigid case by introducing the set \mathbb{E} as the new set of directed edges of G (the cardinality of \mathbb{E} is twice that of E), denoting by $\bar{e} \in \mathbb{E}$ the inverse of the directed edge $e \in E$ and requiring $f(\bar{e}) = -f(e)$, [1, 12].
- 3. The graph G is undirected. The value of a function f on an edge e does not depend on the direction of the travel on e. The case of balanced functions f : E → ℝ is studied in [2], where these functions are called "cycle-vanishing edge valuations". The case of balanced functions f : E → A is studied in [7]. The case of balanced functions f : V ∪ E → A is first introduced and studied in [9]. The group structure of the groups of balanced functions on the edges, balanceable functions on the vertices and balanced functions on the vertices and edges of an undirected graph with values in an Abelian group is studied in [7].

The subject of this paper is the group structure and the relations between groups of functions associated with the notion of balance on a directed graph. Namely, we study the group structures of the groups of balanced functions for the flexible and the rigid cases and the relations between these two cases.

In this article we calculate the groups of balanced functions on the edges, balanceable functions on the vertices and balanced functions on the vertices and edges of a directed graph with values in an Abelian group for both flexible and rigid cases.

In what follows, we say that a directed graph is *connected* if its underlying undirected graph is connected, and *strongly connected* whenever there exists a directed path between any ordered pair of vertices.

For the basics of Graph Theory we refer to [8].

2 The flexible case

Let G = (V, E) be a connected directed graph, possibly with loops and multiple edges. Let v and w be two vertices connected by an edge e; v is the origin of e and w is the endpoint of e. For $e \in E$ denote by \bar{e} the same edge as e but taken in the opposite direction. Thus \bar{e} goes from w to v. Let $\mathbb{E} = \{e, \bar{e} \mid e \in E\}$.

Definition 2.1. A *path* from a vertex x to a vertex y is an alternating sequence $v_1, e_1, v_2, e_2,...,v_n, e_n$ of vertices from V and different edges from \mathbb{E} such that $v_1 = x$ and each e_j , for j = 1, ..., n - 1, goes from v_j to v_{j+1} and e_n goes from v_n to y. We permit the same edge e to appear in a path twice - one time along and one time against its direction, since this is regarded as using two different edges from \mathbb{E} .

We require our graphs to be connected. Namely, any two different vertices of the graph G can be connected by a path.

Definition 2.2. A cycle is a path from a vertex to itself.

We permit the trivial cycle, which is the empty sequence containing no vertices and no edges.

Definition 2.3. The *length* of a cycle is the number of its edges.

Definition 2.4. A function $f : \mathbb{E} \to A$ such that $f(\bar{e}) = -f(e)$ is *balanced* if the sum $f(e_1) + \ldots + f(e_n)$ of the values of f over all the edges of any cycle of G is equal to 0.

Definition 2.5. The set of all the balanced functions $f : \mathbb{E} \to A$ is denoted by $\mathcal{HF}(\mathbb{E}, A)$. $\mathcal{HF}(\mathbb{E}, A)$ is a subgroup of the Abelian group $A^{\mathbb{E}}$ of all the functions from \mathbb{E} to A.

Definition 2.6. A function $g: V \to A$ is *balanceable* if there exists some $f: \mathbb{E} \to A$ such that $f(\overline{e}) = -f(e)$ and the sum of all the values $g(v_1) + f(e_1) + g(v_2) + f(e_2) + ... + g(v_n) + f(e_n)$ along any cycle of G is zero. We say that this function $f: \mathbb{E} \to A$ balances the function $g: V \to A$.

Definition 2.7. The set of all the balanceable functions $g: V \to A$ is denoted by $\mathcal{BF}(V, A)$. The group $\mathcal{BF}(V, A)$ is a subgroup of the free Abelian group A^V of all the functions from V to A.

Definition 2.8. A function $h: V \bigcup \mathbb{E} \to A$, which takes both vertices and edges of G to some elements of A, is *balanced* if $h(\bar{e}) = -h(e)$ and the sum of its values $h(v_1) + h(e_1) + h(v_2) + h(e_2) + ... + h(v_n) + h(e_n)$ along any cycle of G is zero.

Definition 2.9. The set of all the balanced functions $h : V \bigcup \mathbb{E} \to A$ is denoted by $\mathcal{WF}(G, A)$. The group $\mathcal{WF}(G, A)$ is a subgroup of the Abelian group $A^{V \bigcup \mathbb{E}}$ of all the functions from $V \bigcup \mathbb{E}$ to A.

Clearly, any balanced function $f \in \mathcal{HF}(\mathbb{E}, A)$ can be viewed as a balanced function from $V \bigcup \mathbb{E}$ to A, which takes zero value on every vertex of G. Thus, we will regard $\mathcal{HF}(\mathbb{E}, A)$ as a subgroup of $\mathcal{WF}(V \bigcup \mathbb{E}, A)$.

Proposition 2.10. The quotient $W\mathcal{F}(V \bigcup \mathbb{E}, A)/\mathcal{HF}(\mathbb{E}, A)$ is naturally isomorphic to $\mathcal{BF}(V, A)$.

Proof. The natural isomorphism is defined by "forgetting" the values of $h \in W\mathcal{F}(V \bigcup \mathbb{E}, A)$ on the edges of G and regarding it just as a balanceable function from V to A.

We review some basic definitions and facts regarding Abelian groups.

Definition 2.11. A natural number k is the *order* of an element $a \in A$ if it is the minimal positive integer such that $k \cdot a = 0$.

Definition 2.12. The set of all elements of A of order 2 is denoted by A_2 . The set A_2 is a subgroup of A.

We provide a proof of a folklore result which describes the structure of the group $\mathcal{HF}(\mathbb{E}, A)$.

Proposition 2.13. The group $\mathcal{HF}(\mathbb{E}, A)$ is isomorphic to $A^{|V|-1}$.

Proof. Select a vertex v and consider the following bijection between the group of all A-valued functions g on V with g(v) = 0 and the group $\mathcal{HF}(\mathbb{E}, A)$. For any such g, since each edge $e \in \mathbb{E}$ goes from some vertex x to some vertex y, we define f(e) = g(y) - g(x). A straightforward calculation shows that $f \in \mathcal{HF}(\mathbb{E}, A)$. In the other direction of the bijection, for $f \in \mathcal{HF}(\mathbb{E}, A)$ we inductively construct the function g as follows: we set g(v) = 0; if g(u) has been defined for a vertex u then for every vertex w, for which there exists some edge e from u to w, we define g(w) = g(u) + f(e). Since $f \in \mathcal{HF}(\mathbb{E}, A)$, any two calculations of the value of g on any vertex u will produce the same result. The connectivity implies that every vertex indeed receives a value. Thus, our g is well-defined. Obviously, the bijection, constructed above, is a group isomorphism.

Now we can state and prove one of our main results.

Theorem 2.14. Let G = (V, E) be a connected directed graph and G' be its underlying undirected graph. Then:

- 1. If G' is bipartite, then the group $\mathcal{WF}(V \cup \mathbb{E}, A)$ is isomorphic to $A^{|V|}$.
- 2. If G' is not bipartite, then $W\mathcal{F}(V \mid J\mathbb{E}, A)$ is isomorphic to $A_2 \times A^{|V|-1}$.

Proof. If G consists only of one vertex then part (1) of our theorem is trivial. Otherwise, let us look at any one non-loop edge of G as it is depicted in Fig. 1:

$$a \xrightarrow{p} b$$

Figure 1: An edge with values on it and on its origin and end.

The letters on the edge and the vertices denote the values of a function $h : V \bigcup \mathbb{E} \to A$. Assume that h is balanced, that is, $h \in W\mathcal{F}(V \bigcup \mathbb{E}, A)$. Then for the cycle obtained by walking along this edge and returning back along it we have the following equation:

$$a+p+b-p=0 ,$$

which immediately implies that

b = -a.

Thus h must have opposite values on any two vertices of G connected by an edge. Assume that G' is bipartite, which implies that G has no cycles of odd length. Then h, restricted to the edges, must be equal to some balanced function $f \in \mathcal{HF}(\mathbb{E}, A)$ on the edges, since values a and -a on the vertices of an even-length cycle appear equally often. Now select any vertex $v \in V$. We can construct a balanced function h on vertices and edges by: for any element $a \in A$ define h(v) = a and then define h for all the neighbors of v to be -a and then for all the neighbors of the neighbors of v define h to be a and so on. Continuing this way we will assign values a or -a to all the vertices of G. Since all the cycles are of even length, we will not get a contradiction in that process. Next we choose any function $f \in \mathcal{HF}(\mathbb{E}, A)$ and we set h on the edges to be equal to f. Hence, we have constructed a bijection between $\mathcal{WF}(V \bigcup \mathbb{E}, A)$ and the group of pairs $\{(a, f) \mid a \in A, f \in \mathcal{HF}(\mathbb{E}, A)\}$. This bijection is obviously also a group isomorphism. In addition, $\{(a, f) \mid a \in A, f \in \mathcal{HF}(\mathbb{E}, A)\}$ is isomorphic to $A^{|V|}$, since the group $\mathcal{HF}(\mathbb{E}, A)$ is isomorphic to $A^{|V|-1}$ by Proposition 2.13.

Now assume that G' is not bipartite, that is, G has a cycle of odd length. As we have already seen above, the values of a balanced function $h \in \mathcal{WF}(V \bigcup \mathbb{E}, A)$ on the vertices must be a and -a for some $a \in A$. But walking along a cycle of odd length with vertices $v_1, v_2,...,v_n$, we get $h(v_1) = a$, $h(v_2) = -a,..., h(v_n) = a$, $h(v_1) = -a$, so a = -a, that is, 2a = 0, which exactly means that $a \in A_2$. Thus we construct a bijection between $\mathcal{WF}(V \bigcup \mathbb{E}, A)$ and the group of pairs $\{(a, f) \mid a \in A_2, f \in \mathcal{HF}(\mathbb{E}, A)\}$ mapping $h \in$ $\mathcal{WF}(V \bigcup \mathbb{E}, A)$ to the pair (a, f), where $a \in A_2$ is the value of h on any vertex, and f is a balanced function on edges defined as f(e) = h(e) + a for every edge e; conversely, from a given $a \in A_2$ and a balanced function $f \in \mathcal{HF}(\mathbb{E}, A)$, we can construct a balanced function $h \in \mathcal{WF}(V \bigcup \mathbb{E}, A)$ assuming h(v) = a for any vertex v and h(e) = f(e) + a for any edge e. This bijection is a group isomorphism. In addition, $\{(a, f) \mid a \in A_2, f \in \mathcal{HF}(\mathbb{E}, A)\}$ is isomorphic to $A_2 \times A^{|V|-1}$, since the group $\mathcal{HF}(\mathbb{E}, A)$ is isomorphic to $A^{|V|-1}$ by Proposition 2.13.

Remark 2.15. Let G = (V, E) be a connected directed graph and G' be its underlying undirected graph. Notice that if the graph G' is bipartite, then the group of balanceable functions $\mathcal{BF}(V, A)$ is isomorphic to A and if G' is not bipartite, then the group of balanceable functions $\mathcal{BF}(V, A)$ is isomorphic to A_2 - the group of involutions of A.

3 The rigid case

Let G = (V, E) be a connected directed graph. Recall that in the rigid case we are allowed to walk only in the direction of an edge but not against it. It naturally changes the notion of a path and of a cycle in comparison with the flexible case.

Definition 3.1. A *path* from a vertex x to a vertex y is an alternating sequence v_1 , e_1 , v_2 , $e_2,...,v_n$, e_n of vertices from V and different edges from E (and not \mathbb{E}) such that $v_1 = x$ and each e_j , for j = 1, ..., n - 1, goes from v_j to v_{j+1} and e_n goes from v_n to y.

For example, the triangle depicted in Fig. 2 is a cycle in the flexible case but is not a cycle in the rigid case.

Similarly to the flexible case denote by $\mathcal{BR}(V, A)$, $\mathcal{HR}(E, A)$ and $\mathcal{WR}(V \bigcup E, A)$ the groups of balanceable functions on vertices, balanced functions on edges and balanced functions of the entire graph G (vertices and edges), respectively.



Figure 2: A flexible cycle, which is not a rigid cycle.

Proposition 3.2. Every function on the set of vertices is balanceable. That is,

$$\mathcal{BR}(V,A) = A^V.$$

Proof. Let us take a function $g: V \to A$. Define the function $h: V \bigcup E \to A$ in the following way: h(v) = g(v) for each vertex $v \in V$, h(e) = -g(v) for all the edges $e \in E$ which start at v. Obviously h is a balanced function.

Definition 3.3. Two vertices x and y of G are strongly connected if there exists a path P_1 from x to y and a path P_2 from y to x. We also say that every vertex is strongly connected to itself.

Notice that we allow P_1 and P_2 to have common edges.

Definition 3.4. A cycle is a path P from a vertex x to itself.

Notice that, since the paths P_1 and P_2 mentioned above might have common edges, P_1 followed by P_2 may not be a cycle. It can even happen, that there exists no cycle, which contains both x and y. To illustrate it, consider the following.

Example 3.5. Consider the graph G depicted in Fig. 3 with $V(G) = \{x, v, w, y\}$ and $E(G) = \{e_1, e_2, e_3, e_4, e_5\}$. The path $P_1 = x, e_1, v, e_5, w, e_4$ is the only path which goes from x to y and the path $P_2 = y, e_2, v, e_5, w, e_3$ is the only path which goes from y to x. They have a common edge e_5 . Thus, according to Definitions 3.1 and 3.4, there exists no cycle containing both x and y.



Figure 3: The vertices x, y are strongly connected but no cycle contains both of them.

Strong connectivity defines an equivalence relation on the vertices of G. The equivalence classes of strongly connected vertices, together with all the edges between the vertices of each class, are called the *strongly connected* components of G. We denote the number

of strongly connected components of G by $\bar{k}(G)$. Obviously, G is strongly connected if and only if $\bar{k}(G) = 1$.

Lemma 3.6. If G is strongly connected, then the group $\mathcal{HR}(E, A)$ is isomorphic to $A^{|V|-1}$, just like in the flexible case.

Proof. Let $E = \{e_1, ..., e_n\}$. The edge e_1 goes from some x to some y. There is a path P which goes from y to x and does not contain e_1 , since if P contains e_1 we can just delete this e_1 and all the vertices and edges that come after it from P. Thus, the sum of values of any $f \in \mathcal{HR}(E, A)$ along P must be equal to $-f(e_1)$. Hence, we can add a new edge $\overline{e_1}$ to G which goes from y to x and we can extend the function f to a balanced function on the edges of the new G if and only if we set $f(\overline{e_1}) = -f(e_1)$. So the group of the balanced functions on the edges of G after the addition of $\overline{e_1}$ is naturally isomorphic to the original group of the balanced functions on the edges of G to the flexible case, while not changing the group of the balanced functions on the edges of G.

Theorem 3.7. The group $\mathcal{HR}(E, A)$ is isomorphic to $A^{|V|-\bar{k}(G)+r(G)}$, where $\bar{k}(G)$ is the number of strongly connected components of G, and r(G) is the number of all the edges in G which go from a vertex in one strongly connected component of G to a vertex in a different strongly connected component of G.

Proof. Let $V_1, ..., V_t$ be the equivalence classes of vertices of G with respect to strong connectivity. Denote the set of edges between the vertices of V_j by E_j . Obviously, $f \in \mathcal{HR}(E, A)$ if and only if $f|_{E_j} \in \mathcal{HR}(E_j, A)$ for each $j, 1 \leq j \leq t$. Thus, $\mathcal{HR}(E, A) = \mathcal{HR}(E_1, A) \times \cdots \times \mathcal{HR}(E_t, A) \times A^U$, where U is the set of all the edges between the vertices in different strongly connected components of G. By Lemma 3.6 we conclude that $\mathcal{HR}(E, A)$ is isomorphic to $A^{|V_1|-1+|V_2|-1+\cdots+|V_t|-1+r(G)} = A^{|V|-\bar{k}(G)+r(G)}$.

Theorem 3.8. The group $W\mathcal{R}(V \bigcup E, A)$ is isomorphic to $A^{2|V|-\bar{k}(G)+r(G)}$, where $\bar{k}(G)$ is the number of strongly connected components of G, and r(G) is the number of all the edges in G which go from a vertex in one strongly connected component of G to a vertex in a different strongly connected component of G.

Proof. To each $h \in W\mathcal{R}(V \cup E, A)$ there corresponds the pair (g, f), where $g \in \mathcal{BR}(V, A)$ is just the restriction of h on the vertex set, and the value of $f \in \mathcal{HR}(E, A)$ on every edge e is equal to h(e) + h(v), where the vertex v is the origin of the edge e. Such a function f is obviously a balanced function on the edge set since its value along any path is equal to the value of h along that path. This correspondence between the elements of $W\mathcal{R}(V \cup E, A)$ and the pairs from $\mathcal{BR}(V, A) \times \mathcal{HR}(E, A)$ is a bijection. Indeed, for a given pair (g, f), where g is any function on the vertex set and f is a balanced function on the edge set, we can construct $h : V \cup E \to A$ as follows: h(v) = g(v) for all $v \in V$ and h(e) = f(e) - g(v) for all $e \in E$, where the vertex v is the origin of the edge e. The constructed bijection is obviously a group isomorphism between the group $W\mathcal{R}(V \cup E, A)$ and the group $\mathcal{BR}(V, A) \times \mathcal{HR}(E, A)$, which is isomorphic to $A^{|V|} \times A^{|V|-\bar{k}(G)+r(G)}$. □

Thus, the flexible problem for a graph G = (V, E) can be regarded as the rigid problem for the graph $G' = (V, \mathbb{E})$, where $\mathbb{E} = \{e, \overline{e} \mid e \in E\}$. Vice versa, the rigid problem for a graph G can be regarded as a free product of the rigid problems for the strongly connected components of G also multiplied by $A^{r(G)}$ where r(G) is the number of edges between different strongly connected components of G.

The following simple claim connects this work to [7].

Proposition 3.9. Let G be an undirected connected graph and let G_{dir} be a directed graph obtained from G by any assignment of directions to the edges of G. Denote by H(E, A) the group of A-valued balanced functions on edges of G. Choose any order on edges of G and embed H(E, A) and $\mathcal{HR}(E(G_{dir}), A)$ into $A^{|E|}$. For an undirected graph G the group of balanced functions on edges of G is equal to the intersection of all the groups $\mathcal{HR}(E(G_{dir}), A)$, where G_{dir} runs over all directed graphs for all $2^{|E|}$ possible direction assignments to the edges of G. The same is true for the groups of balanced functions on the entire graph (both vertices and edges). Namely, $W(V \bigcup E, A) = \bigcap \mathcal{WR}(V \bigcup E(G_{dir}), A)$.

Proof. Let $Cyc = v_1, e_1, ..., v_k, e_k$ be a cycle in the undirected graph G. There exists a directed graph G_{dir} for which c is also a cycle. So any $f \in \bigcap \mathcal{HR}(E(G_{dir}), A)$ must satisfy the equation $\sum_{i=1}^{k} f(e_i) = 0$. Therefore $f \in H(E, A)$, since Cyc is an arbitrary cycle of G. Hence,

$$H(E,A) \supseteq \bigcap \mathcal{HR}(E(G_{dir}),A).$$

The opposite inclusion is obvious, since any cycle of any G_{dir} is a cycle of G. The proof of the second statement of the proposition is similar.

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