

Small Label Classes in 2-Distinguishing Labelings

Debra L. Boutin

Hamilton College, Clinton, NY 13323, USA

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Abstract

A graph G is said to be *2-distinguishable* if there is a labeling of the vertices with two labels so that only the trivial automorphism preserves the labels. Call the minimum size of a label class in such a labeling of G the *cost of 2-distinguishing G* and denote it by $\rho(G)$. This paper shows that for $n \geq 5$, $\lceil \log_2 n \rceil + 1 \leq \rho(Q_n) \leq 2\lceil \log_2 n \rceil - 1$, where Q_n is the hypercube of dimension n .

Keywords: Graph, distinguishing labeling, automorphism group.

Math. Subj. Class.: 05C15, 05C25

1 Introduction

A labeling of the vertices of a graph G with the integers $1, \dots, d$ is called a *d -distinguishing labeling* if no nontrivial automorphism of G preserves the labels. A graph is called *d -distinguishable* if it has a d -distinguishing labeling. Albertson and Collins introduced distinguishing in [2]. Recent work shows that large members of many infinite families of graphs are 2-distinguishable. These graph families include hypercubes Q_n with $n \geq 4$ [3], nontrivial Cartesian powers of a connected graph $G \neq K_2, K_3$ [8], Kneser graphs $K_{n:k}$ with $n \geq 6, k \geq 2$ [1], and (with seven small exceptions) 3-connected planar graphs [6]. Recently Wilfried Imrich posed the following question: “What is the minimum number of vertices in a label class of a 2-distinguishing labeling for the hypercube Q_n ?” This question can be extended to any family of 2-distinguishable graphs.

Let G be a 2-distinguishable graph. Call a label class in a 2-distinguishing labeling of G a *distinguishing class*. Call the minimum size of such a class in G the *cost of 2-distinguishing G* and denote it by $\rho(G)$. The labeling provided for Q_n by Bogstad and Cowan in [3] shows that for $n \geq 4$, $\rho(Q_n) \leq n + 2$. The best result known when Imrich posed the question mentioned above was $\rho(Q_n) \approx \sqrt{n}$ [7]. For $n \geq 5$, this paper shows that $\rho(Q_n) \leq 2\lceil \log_2 n \rceil - 1$ and that this is within a factor of two of a natural lower bound (discussed below). To give a sense

E-mail address: dboutin@hamilton.edu (Debra L. Boutin)

of this result, note that though Q_{16} has 2^{16} vertices and $16! \times 2^{16}$ automorphisms, it can be distinguished, effectively eliminating all symmetry, by coloring just seven vertices red and all others blue.

A significant tool used in this work is the *determining set* [4], a set of vertices whose pointwise stabilizer is trivial. Albertson and Boutin showed that a graph is d -distinguishable if and only if it has a determining set that is $(d - 1)$ -distinguishable [1]. When $d = 2$ this translates as: a graph is 2-distinguishable if and only if it has a determining set with the property that any automorphism that preserves the set must fix it pointwise. This shows that $\rho(G)$ is bounded below by the size of a smallest determining set for G . For Q_n this bound is $\lceil \log_2 n \rceil + 1$ [5]. We will use the connection between determining sets and distinguishing labelings, along with particular determining sets found in [5], to create a distinguishing class for Q_n that is smaller than twice this lower bound.

The paper is organized as follows. Definitions and facts about determining sets, Cartesian products, and distinguishing labelings are given in Section 2. This section also sets out the key idea tying together determining sets and distinguishing labelings. For $n \geq 5$, Section 3 gives a set of $2^{\lceil \log_2 n \rceil} - 1$ vertices of Q_n and proves that it is a distinguishing class. Section 4 lists some open questions.

2 Background

2.1 Determining Sets

Let G be a graph. A subset $U \subseteq V(G)$ is said to be a *determining set* for G if whenever $g, h \in \text{Aut}(G)$ and $g(x) = h(x)$ for all $x \in U$, then $g = h$. Thus every automorphism of G is uniquely determined by its action on a determining set. Every graph has a determining set since any set containing all but one vertex is determining. There are graphs, e.g. K_n and $K_{1,n}$, for which such a determining set is optimal or within one of being optimal. The *determining number* of G , denoted here by $\text{Det}(G)$, is the minimum r such that G has a determining set of cardinality r .

Recall that the *set stabilizer* of $U \subseteq V(G)$ is the set of all $\phi \in \text{Aut}(G)$ for which $\phi(x) \in U$ for all $x \in U$. In this case we say that $\phi(U) = U$. The *pointwise stabilizer* of U is the set of all $\phi \in \text{Aut}(G)$ for which $\phi(x) = x$ for all $x \in U$. It is easy to see that $U \subseteq V(G)$ is a determining set for G if and only if the pointwise stabilizer of U is trivial.

2.2 Cartesian Products

Recall that the *Cartesian product* of graphs G and H , denoted by $G \square H$, has vertex set $V(G) \times V(H)$ with an edge between vertices (x, u) and (y, v) if either x is adjacent to y in G and $u = v$, or u is adjacent to v in H and $x = y$. The *Cartesian power* H^k is the Cartesian product of H with itself k times.

A good reference for Cartesian products is [9]. Recall that H is *prime* with respect to the Cartesian product if it cannot be written as the Cartesian product of two smaller graphs. Further, every connected graph can be written uniquely (up to order) as the Cartesian product of prime factors, $G = G_1 \square \cdots \square G_m$.

Let $U = \{V_1, \dots, V_r\}$ be an ordered subset of vertices of $G = G_1 \square \cdots \square G_m$. Let $M = M_U$ be the $r \times m$ matrix whose i^{th} row contains the coordinates for V_i with respect

to the prime factor decomposition of G . Call this the *characteristic matrix* for U . Note that the j^{th} column of M consists of the j^{th} coordinates of V_1, \dots, V_r and can be denoted $[V_{1,j} \dots V_{r,j}]^T$. We say the j^{th} and k^{th} columns of M , $[V_{1,j} \dots V_{r,j}]^T$ and $[V_{1,k} \dots V_{r,k}]^T$, are *isomorphic images of each other* if there exists an isomorphism $\varphi : G_j \rightarrow G_k$ so that $\varphi(V_{i,j}) = V_{i,k}$ for all i . These definitions allow us to state criteria for a set to be a determining set as follows.

Lemma 1. [5] Let G be a connected graph and $G = G_1 \square \dots \square G_m$ the prime factor decomposition for G with respect to the Cartesian product. A set of vertices U is a determining set for G if and only if each column of the characteristic matrix M for U contains a determining set for the appropriate factor of G and no two columns of M are isomorphic images of each other.

2.3 Distinguishing Labelings

A labeling $f : V(G) \rightarrow \{1, \dots, d\}$ is said to be *d-distinguishing* if $\phi \in \text{Aut}(G)$ and $f(\phi(x)) = f(x)$ for all $x \in V(G)$ implies that $\phi = \text{id}$. Every graph has a distinguishing labeling since each vertex can be assigned a distinct label. Furthermore, there are graphs, e.g. K_n and $K_{1,n}$, for which such a labeling is optimal or within one of being optimal. A graph is called *d-distinguishable* if it has a *d-distinguishing* labeling.

We will also need to know what it means for a subset of vertices to be *d-distinguishable*. Let $U \subseteq V(G)$. A labeling $f : U \rightarrow \{1, \dots, d\}$ is called *d-distinguishing* if whenever $\phi \in \text{Aut}(G)$ so that $\phi(U) = U$ and $f(\phi(x)) = f(x)$ for all $x \in U$ then $\phi(x) = x$ for all $x \in U$. Note that though such a ϕ fixes U pointwise, it is not necessarily trivial; it may permute vertices in the complement of U . Then by definition, U is 1-distinguishable if every automorphism that preserves U fixes it pointwise.

The following theorem ties together determining sets and distinguishing labelings and facilitates the work in this paper.

Theorem 2. [1] A graph is *d-distinguishable* if and only if it has a determining set that is $(d - 1)$ -distinguishable.

In particular, suppose U is a 1-distinguishable determining set. The fact that it is 1-distinguishable means that any automorphism that preserves U as a set also fixes it pointwise. The fact that it is a determining set means that the only automorphism that fixes it pointwise is the trivial automorphism. Thus if we label the vertices of U with ones and the vertices of its complement with twos, only the trivial automorphism preserves the label classes. Therefore U is a distinguishing class of a 2-distinguishing labeling. Thus to find a distinguishing class, we will look for a (small) determining set for which no nontrivial automorphism both preserves the set and permutes vertices within the set. One can think of such a set as having no “internal symmetry.”

3 The Hypercubes

Recall that the n -cube, or hypercube of dimension n , is the Cartesian product of K_2 with itself n times. That is, $Q_n = K_2^n$. Thus we can represent the vertices of Q_n as strings of n zeros and ones. For $n \geq 5$ we will construct a distinguishing class of size $2^{\lfloor \log_2 n \rfloor} - 1$ for Q_n . We will start by defining a set $U_r \subseteq V(Q_{2^r})$ for $r \geq 3$. In Theorem 5 we will show that

U_r is indeed a distinguishing class for Q_{2^r} . In Theorem 6 we will show that if $r = \lceil \log_2 n \rceil$ the same is true for the projection of U_r into Q_n obtained by projecting each vertex onto its first n coordinates.

First let us define U_r . For $0 \leq k \leq r$, we call each of the 2^{r-k} consecutive sequences of 2^k coordinates in a vertex of Q_{2^r} a *block* of length 2^k . For $i = 1, \dots, r$, let V_i be the vertex of Q_{2^r} consisting of blocks of 2^{i-1} ones alternating with blocks of 2^{i-1} zeros. Let V_0 be the vertex with one in its second coordinate and zeros in all others. For $i = 1, \dots, r-2$, let X_i be the vertex of Q_{2^r} that agrees with V_i and V_{i+1} on the coordinates in which they agree and that has a one in every other coordinate. We can think of X_i as the “OR” of V_i and V_{i+1} ; it has a one in a coordinate if either V_i or V_{i+1} has a one there, and a zero otherwise. Alternately, X_i can be described as having the repeating pattern: three blocks of 2^{i-1} ones followed by one block of 2^{i-1} zeros. Let $U = U_r = \{V_0, \dots, V_r, X_1, \dots, X_{r-2}\}$

Example 3. U_4 contains the following vertices.

$$\begin{aligned} V_0 &= 0100000000000000 \\ V_1 &= 1010101010101010 \\ V_2 &= 1100110011001100 \\ V_3 &= 1111000011110000 \\ V_4 &= 1111111100000000 \\ X_1 &= 1110111011101110 \\ X_2 &= 1111110011111100 \end{aligned}$$

The proofs of Theorems 5 and 6 make extensive use of distances between elements of U . Due to the repeating nature of the coordinates of our vertices, these distances are reasonable to compute. The details are given below and are summarized in Table 1.

Consider $d(V_i, V_j)$ where $1 \leq i < j \leq r$. Each block of length 2^{j-1} in V_j (which contains only zeros or only ones) corresponds to 2^{j-i} blocks of length 2^{i-1} in V_i (which alternate between ones blocks and zeros blocks). Thus V_i and V_j disagree in half their coordinates. Therefore $d(V_i, V_j) = 2^{r-1}$ for $1 \leq i < j \leq r$.

Consider $d(X_i, V_i)$ and $d(X_i, V_{i+1})$ where $1 \leq i \leq r-2$. Note that since $i \geq 1$, precisely half the coordinates of V_i that disagree with V_{i+1} are zeros and thus disagree with X_i also. The same statement holds for V_{i+1} . Thus $d(X_i, V_i) = d(X_i, V_{i+1}) = \frac{1}{2}d(V_i, V_{i+1}) = 2^{r-2}$ for $1 \leq i \leq r-2$.

Consider $d(X_i, X_{i+1})$ where $1 \leq i \leq r-3$. There are eight blocks of length 2^{i-1} in X_i to every four blocks of length 2^i of X_{i+1} . By comparing the repeating patterns of these blocks we see that X_i and X_{i+1} disagree on the 4th and 7th of these eight blocks. Thus $d(X_i, X_{i+1}) = \frac{2}{8}2^r = 2^{r-2}$ for $1 \leq i \leq r-3$.

Consider $d(X_i, X_j)$ where $1 \leq i \leq j-2 \leq r-4$. Since $i \leq j-2$, an integer multiple of four blocks of X_i correspond to a single block of zeros or ones in X_j . The four block pattern of X_i disagrees $\frac{1}{4}$ of the time with a ones block of X_j and $\frac{3}{4}$ of the time with a zeros block of X_j . Since $\frac{3}{4}$ of the blocks of X_j are ones and $\frac{1}{4}$ are zeros, we get that X_i and X_j disagree $\frac{3}{4} \cdot \frac{1}{4} + \frac{1}{4} \cdot \frac{3}{4} = \frac{3}{8}$ of the time. Thus $d(X_i, X_j) = 3 \cdot 2^{r-3}$ for $1 \leq i \leq j-2 \leq r-4$.

Consider $d(X_i, V_j)$ where $1 \leq i \leq j-2 \leq r-2$. Again since $i \leq j-2$, an integer multiple of four blocks of X_i corresponds to a single block of V_j . The four block pattern of

X_i disagrees with ones blocks and zeros blocks as described above. However, V_j has half its blocks ones and half zeros. Thus X_i and V_j disagree $\frac{1}{2} \cdot \frac{1}{4} + \frac{1}{2} \cdot \frac{3}{4} = \frac{1}{2}$ the time. Thus $d(X_i, V_j) = \frac{1}{2} \cdot 2^r = 2^{r-1}$ for $1 \leq i \leq j - 2 \leq r - 2$.

Consider $d(V_i, X_j)$ where $1 \leq i \leq j - 1 \leq r - 3$. Since $i \leq j - 1$, an integer multiple of two blocks of V_i correspond to a single block of X_j . Such a pair of blocks disagrees with a single block of X_j precisely half the time. Thus $d(X_i, V_j) = 2^{r-1}$ for $1 \leq i \leq j - 1 \leq r - 3$.

Consider $d(V_0, V_i)$ where $1 \leq i \leq r$. Since for $i \geq 1$, V_i has exactly half of its coordinates zero, if V_0 consisted of all zeros we would have $d(V_0, V_i) = 2^{r-1}$. However since the second coordinate of V_0 is one, which disagrees with the second coordinate of V_1 and agrees with all other V_i we have that $d(V_0, V_1) = 2^{r-1} + 1$, and $d(V_0, V_i) = 2^{r-1} - 1$ for $2 \leq i \leq r$.

Consider $d(V_0, X_i)$ where $1 \leq i \leq r - 2$. Because X_i has three blocks of ones followed by one block of zeros, X_i has three quarters of its coordinates ones. Adjusting for the one in the second coordinate of V_0 yields $d(V_0, X_i) = \frac{3}{4}2^r - 1 = 3 \cdot 2^{r-2} - 1$ for $1 \leq i \leq r - 2$.

Note that the only pairs of vertices of U at distance 2^{r-2} are $\{X_i, V_i\}$, $\{X_i, V_{i+1}\}$, and $\{X_i, X_{i+1}\}$. We will call these *related pairs* because they have the distance relationship we will use to show that U is 1-distinguishable. Other pairs of vertices in U are called *non-related pairs*.

Related Pairs

$d(X_i, V_i)$	2^{r-2}	for $1 \leq i \leq r - 2$
$d(X_i, V_{i+1})$	2^{r-2}	for $1 \leq i \leq r - 2$
$d(X_i, X_{i+1})$	2^{r-2}	for $1 \leq i \leq r - 3$

Non-Related Pairs

$d(V_0, X_i)$	$3 \cdot 2^{r-2} - 1$	for $1 \leq i \leq r - 2$
$d(V_0, V_1)$	$2^{r-1} + 1$	
$d(V_i, V_j)$	2^{r-1}	for $1 \leq i < j \leq r$
$d(X_i, V_j)$	2^{r-1}	for $1 \leq i \leq r - 2, 1 \leq j \leq r,$ $j \neq i, i + 1$
$d(V_0, V_i)$	$2^{r-1} - 1$	for $2 \leq i \leq r$
$d(X_i, X_j)$	$3 \cdot 2^{r-3}$	for $1 \leq i \leq j - 2 \leq r - 4$

Table 1: Distances in Q_{2^r}

Before stating and proving Theorem 5, we will prove that U is a determining set for Q_{2^r} . By Lemma 1, U is a determining set for Q_{2^r} if and only if each column of the characteristic matrix for U contains a determining set for its associated prime factor and no two columns are isomorphic images of each other. Since any single vertex is a determining set for K_2 , here we need only show that no two columns of M_U are isomorphic images of each other.

Let M_U be the characteristic matrix for $U = \{V_0, \dots, V_r, X_1, \dots, X_{r-2}\}$ and M_T the

characteristic matrix for $T = \{V_0, \dots, V_r\}$. Note that the matrix M_T is given by the first $r + 1$ rows of M_U . See Example 4 for M_U in the case $r = 4$.

Example 4. The characteristic matrix for U_4 .

$$\begin{matrix} V_0 \\ V_1 \\ V_2 \\ V_3 \\ V_4 \\ X_1 \\ X_2 \end{matrix} \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 0 & 1 & 1 & 1 & 0 & 1 & 1 & 1 & 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 & 1 & 1 & 1 & 1 & 1 & 1 & 0 & 0 \end{bmatrix}$$

By the proof of [5, Theorem 3], if we take T and replace V_0 with the vertex of all zeros, we get a determining set for Q_{2^r} . This means that if we change the entry in the first row second column of M_T to a zero, we would have a characteristic matrix in which no pair of columns are isomorphic images of each other. Thus in M_T the only pairs of columns that might be isomorphic images of each other are pairs involving the second column. Note that the second column, $[1\ 0\ 1\ 1\ \dots\ 1]^T$, and the $(2^r - 1)^{st}$ column, $[0\ 1\ 0\ 0\ \dots\ 0]^T$, are isomorphic images of each other under the isomorphism $(0\ 1)$ of K_2 . (Thus T is not a determining set.) If there was another column of M_T isomorphic to the second, it would also be isomorphic to the $(2^r - 1)^{st}$, which we argued cannot happen. Thus the second and $(2^r - 1)^{st}$ columns are the only pair of columns of M_T that are isomorphic images of each other.

Since the first $r + 1$ rows of M_U form M_T , if two columns of M_U are isomorphic images of each other, then so are the corresponding columns in M_T . Thus we only need to check the second and $(2^r - 1)^{st}$ columns of M_U . We have seen that the first $r + 1$ entries in the second and $(2^r - 1)^{st}$ of these columns are isomorphic images of each other under the isomorphism $(0\ 1)$. However, since $r \geq 3$, X_1 exists, provides the $(r + 2)^{nd}$ row of M_U , and has one in each of its second and $(2^r - 1)^{st}$ coordinates. Thus the isomorphism does not continue to the $(r + 2)^{nd}$ entries of these columns. Thus no two columns of M_U are isomorphic images of each other and therefore U is a determining set for Q_{2^r} .

We now have the machinery in place to prove that U_r is a distinguishing class for Q_{2^r} .

Theorem 5. If $r \geq 3$, then Q_{2^r} has a distinguishing class of size $2r - 1$.

Proof. Define $U = U_r \subset Q_{2^r}$ as above. Define the *distance relationship graph* on U , denoted G_U , to be the graph with vertex set U and with edges between two vertices if their distance in Q_{2^r} is 2^{r-2} . The related pairs, $\{X_i, V_i\}$, $\{X_i, V_{i+1}\}$, and $\{X_i, X_{i+1}\}$, are precisely those that are adjacent in the distance relationship graph. In particular, in this distance relationship graph V_0 and V_r are isolated vertices, V_1 and V_{r-1} have degree one, V_2, \dots, V_{r-2} have degree two, X_1, \dots, X_{r-2} have degree greater than two, and there is a connected component induced by $V_1, \dots, V_{r-1}, X_1, \dots, X_{r-2}$ that has \mathbb{Z}_2 symmetry. See Figure 1 for an illustration when $r = 6$.

Since automorphisms necessarily preserve distance, any automorphism in the set stabilizer of U induces an automorphism of the distance relationship graph. But the only nontrivial actions on G_U either transpose V_0 and V_r , or reflect the nontrivial connected component and therefore transpose V_1 and V_{r-1} , or both. Thus any automorphism that preserves U setwise either transposes V_0 and V_r , or V_1 and V_{r-1} , (or both).

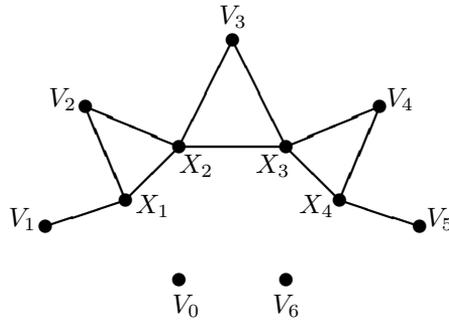


Figure 1: Distance Relationship Graph for U_6

However, for any i , $1 \leq i \leq r - 2$, $d(V_0, X_i) = 3 \cdot 2^{r-2} - 1$ while the distance between V_r and any vertex of $U - \{V_0, V_r\}$ is 2^{r-1} . Thus V_0 achieves distances with vertices of $U - \{V_0, V_r\}$ that are strictly greater than those achieved by V_r . Since automorphisms preserve distance, no automorphism that preserves U can transpose V_0 and V_r . Thus V_0 is distinguished from V_r within U . Further, $d(V_0, V_1) = 2^{r-1} + 1$ and $d(V_0, V_{r-1}) = 2^{r-1} - 1$. Again, since automorphisms preserve distance, no automorphism in the set stabilizer of U can transpose V_1 and V_{r-1} . Thus V_1 and V_{r-1} are distinguished within U .

Thus any automorphism that preserves U must fix U pointwise. Thus U is 1-distinguishable. Recall that before beginning Theorem 5 we proved that U is a determining set. Thus U is a 1-distinguishable determining set, *i.e.* a distinguishing class, of size $2r - 1$ for Q_{2^r} . \square

If $2^{r-1} < n < 2^r$ we will find the desired distinguishing class by projecting U_r into Q_n . The proof that the result is a distinguishing class for Q_n is similar to, but more complex than, the proof for Q_{2^r} .

Theorem 6. If $n \geq 5$, then Q_n has a distinguishing class of size $2\lceil \log_2 n \rceil - 1$.

Proof. By Theorem 5, we get the desired result when $n = 2^r$ for $r \geq 3$. For $n \geq 5$ and not a power of two, there is some $r \geq 3$ for which $2^{r-1} < n < 2^r$. For such an n , let p_n be the projection of Q_{2^r} onto Q_n by projecting each vertex onto its first n coordinates. Let $U = U_r$. Here our goal is to show that $p_n(U)$ is a 1-distinguishable determining set for Q_n . Note that the characteristic matrix for $p_n(U)$ is formed from the first n columns of the characteristic matrix for U . Since we showed that no two columns in M_U are isomorphic images of each other, no two columns in $M_{p_n(U)}$ are isomorphic images of each other. Thus $p_n(U)$ is a determining set for Q_n .

Consider the possible distances between vertex pairs in Q_n . When we project vertices, say X and Y , from Q_{2^r} into Q_n (or from Q_n into $Q_{2^{r-1}}$) by dropping the appropriate number of rightmost coordinates, we are dropping coordinates in which these vertices may disagree. Thus the distances between projected vertices can only get smaller. In particular the projection of each related pair of U has distance less than or equal to 2^{r-2} in Q_n . Moreover, we conclude that the distance $d(p_n(X), p_n(Y))$ falls between the distance $d(p_{2^{r-1}}(X), p_{2^{r-1}}(Y))$ and the distance $d(X, Y)$ (in Q_{2^r}). Again distances in $Q_{2^{r-1}}$ are not hard to find due to the repeating nature of the coordinates of our vertices. They are contained in Table 2.

Projection of Related Pairs

$d(p_n(X_i), p_n(V_i))$	2^{r-3}	for $1 \leq i \leq r-2$
$d(p_n(X_i), p_n(V_{i+1}))$	2^{r-3}	for $1 \leq i \leq r-2$
$d(p_n(X_i), p_n(X_{i+1}))$	2^{r-3}	for $1 \leq i \leq r-3$

Projection of Non-Related Pairs

$d(p_n(V_0), p_n(V_r))$	$2^{r-1} - 1$	
$d(p_n(V_0), p_n(X_i))$	$3 \cdot 2^{r-3} - 1$	for $1 \leq i \leq r-2$
$d(p_n(V_0), p_n(V_1))$	$2^{r-2} + 1$	
$d(p_n(V_i), p_n(V_j))$	2^{r-2}	for $1 \leq i < j \leq r$
$d(p_n(X_i), p_n(V_j))$	2^{r-2}	for $1 \leq i \leq r-2,$ $1 \leq j \leq r-1,$ $j \neq i, i+1$
$d(p_n(V_0), p_n(V_i))$	$2^{r-2} - 1$	for $2 \leq i \leq r-1$
$d(p_n(X_i), p_n(X_j))$	$3 \cdot 2^{r-4}$	for $1 \leq i \leq j-2 \leq r-4$
$d(p_n(V_r), p_n(X_i))$	2^{r-3}	for $1 \leq i \leq r-2$

Table 2: Distances of projections into Q_n , where $n = 2^{r-1}$

Suppose that the projection of some related pair has distance 2^{r-2} in Q_n . Since this was also their distance in Q_{2^r} this means that the original pair agreed in each of their final $2^r - n$ coordinates. Examining the final blocks of the related pairs we find that the maximum agreement is 2^{r-2} coordinates and occurs only for $\{X_{r-2}, V_{r-2}\}$. In particular if $n < 3 \cdot 2^{r-2}$ then every related pair is at distance less than 2^{r-2} .

We will break this proof into two cases: Case 1: $3 \cdot 2^{r-2} \leq n < 2^r$ and Case 2: $2^{r-1} < n < 3 \cdot 2^{r-2}$. In each case we will define a distance relationship graph on the vertex set $p_n(U)$ similar to the one defined in the proof of Theorem 5. In Case 1 the distance relationship will be “less than or equal to 2^{r-2} ” while in Case 2 the distance relationship will be “strictly less than 2^{r-2} .” These definitions will ensure that related pairs will be adjacent in each distance relationship graph.

By Table 2, the non-related vertices that cannot possibly have distance less than or equal to 2^{r-2} in Q_n where $2^{r-1} < n < 2^r$ are the pairs $\{p_n(V_0), p_n(V_r)\}$, $\{p_n(V_0), p_n(X_i)\}$ where $1 \leq i \leq r-2$, and $\{p_n(V_0), p_n(V_1)\}$. We will analyze the distances between the projections of all other non-related pairs using their distances when projected into $Q_{3 \cdot 2^{r-2}}$. These are given in Table 3.

Case 1: $3 \cdot 2^{r-2} \leq n < 2^r$.

When $3 \cdot 2^{r-2} \leq n < 2^r$, define the distance relationship graph $G_{p_n(U)}$ on $p_n(U)$ so that there is an edge between a pair of vertices when their distance is less than or equal to 2^{r-2} . Since all related pairs fit this distance criterion, $G_{p_n(U)}$ contains G_U (from the proof of Theorem 5) as a subgraph. The distance information from Table 3 allows us to conclude that since $n \geq 3 \cdot 2^{r-2}$ the only edges that might be in $G_{p_n(U)}$ but are not in G_U would be

Projection of Some Non-Related Pairs

$d(p_n(V_{r-1}), p_n(V_r))$	2^{r-1}	
$d(p_n(V_0), p_n(V_{r-1}))$	$2^{r-1} - 1$	
$d(p_n(V_i), p_n(V_j))$	$3 \cdot 2^{r-3}$	for $1 \leq i < j \leq r, i \neq r - 1$
$d(p_n(X_i), p_n(V_j))$	$3 \cdot 2^{r-3}$	for $1 \leq i \leq r - 2,$ $1 \leq j \leq r - 2,$ $j \neq i, i + 1$
$d(p_n(V_r), p_n(X_{r-2}))$	$3 \cdot 2^{r-3}$	
$d(p_n(V_0), p_n(V_i))$	$3 \cdot 2^{r-3} - 1$	for $2 \leq i \leq r - 2$
$d(p_n(X_i), p_n(V_{r-1}))$	$5 \cdot 2^{r-4}$	for $1 \leq i \leq r - 3,$
$d(p_n(V_r), p_n(X_i))$	$5 \cdot 2^{r-4}$	for $1 \leq i \leq r - 3$
$d(p_n(X_i), p_n(X_j))$	$9 \cdot 2^{r-5}$	for $1 \leq i < j - 2 \leq r - 5$
$d(p_n(X_i), p_n(X_{r-2}))$	2^{r-2}	for $1 \leq i \leq r - 4$

Table 3: Some distances of projections into Q_n , where $n = 3 \cdot 2^{r-2}$

between the pairs of the form $\{p_n(X_{r-2}), p_n(X_i)\}$ where $1 \leq i \leq r - 4$. Thus in $G_{p_n(U)}$ the only vertices of degree zero are $p_n(V_0)$ and $p_n(V_r)$, the only vertices of degree one are $p_n(V_1)$ and $p_n(V_{r-1})$, and the vertices of degree two are precisely the vertices $p_n(V_i)$ where $2 \leq i \leq r - 2$.

Recall that since $G_{p_n(U)}$ is defined by distances in Q_n , to prove that $p_n(G)$ is 1-distinguishable in Q_n we can use information from Q_n itself and information from $G_{p_n(U)}$. Notice that in both V_0 and V_r the second 2^{r-1} coordinates are zeros. In particular, their second 2^{r-1} coordinates are the same. Thus distances involving V_0 and V_r are reduced by the same amount in the projection to Q_n . Thus $p_n(V_0)$ still attains greater distances with vertices of $p_n(U) - \{p_n(V_0), p_n(V_r)\}$ than $p_n(V_r)$ can attain. Since automorphisms preserve distance, $p_n(V_0)$ and $p_n(V_r)$ cannot be transposed by any automorphism that preserves $p_n(U)$. (Note that this is true for any $2^{r-1} < n < 2^r$; it will be used again in Case 2.) Thus we can distinguish $p_n(V_0)$ and $p_n(V_r)$ in $p_n(U)$.

If $p_n(V_1)$ and $p_n(V_{r-1})$ have different distances from $p_n(V_0)$ then they are distinguished from each other. However, if $p_n(V_1)$ and $p_n(V_{r-1})$ have the same distance from $p_n(V_0)$, we can replace V_0 (and $p_n(V_0)$) with the vertex of all zeros. This does not change any argument given so far. (The only possible concern is the distance between $p_n(V_0)$ and $p_n(V_1)$. With the change to V_0 , when $n = 2^{r-1}$ the distance between $p_n(V_0)$ and $p_n(V_1)$ drops to 2^{r-2} , which gives $p_n(V_0)$ a neighbor in the distance relationship graph. However, since V_0 and V_1 differ in their $(2^{r-1} + 1)^{st}$ coordinate, when $n > 2^{r-1}$ their distance is still greater than 2^{r-2} .) The change in V_0 will decrease the distance between $p_n(V_0)$ and $p_n(V_1)$ by one and increase the distance between $p_n(V_0)$ and $p_n(V_{r-1})$ by one, thereby distinguishing $p_n(V_1)$ and $p_n(V_{r-1})$. Again, since the only requirement is that $n > 2^{r-1}$, this argument will still be valid in Case 2.

The vertex $p_n(X_1)$ (resp. $p_n(X_{r-2})$) is the only one adjacent to the vertex $p_n(V_1)$ (resp. $p_n(V_{r-1})$) in $G_{p_n(U)}$. Thus $p_n(X_1)$ and $p_n(X_{r-2})$ are distinguished. The vertex $p_n(V_2)$ (resp. $p_n(V_{r-2})$) is the only vertex of degree 2 at distance 2 from $p_n(V_1)$ (resp. $p_n(V_{r-1})$) in $G_{p_n(U)}$. Thus these are also distinguished.

The vertex $p_n(X_2)$ (resp. $p_n(X_{r-3})$) is the only one adjacent to both $p_n(X_1)$ and $p_n(V_2)$ (resp. $p_n(X_{r-2})$) and $p_n(V_{r-2})$) in $G_{p_n(U)}$; thus they are distinguished. Continue in this manner to see that all vertices in $G_{p_n(U)}$ are distinguished. Thus $p_n(U)$ is a 1-distinguishable determining set.

Note that in the argument above we distinguished all of $p_n(U) - \{p_n(V_r)\}$ without using the fact that $p_n(V_r)$ was itself distinguished. Once $p_n(V_0)$ was distinguished, the remainder of $p_n(U) - \{p_n(V_0), p_n(V_r)\}$ could be distinguished. This results in the distinguishing of $p_n(V_r)$ by elimination. This argument will be used again in Case 2 below.

Case 2: $2^{r-1} < n < 3 \cdot 2^{r-2}$.

When $2^{r-1} < n < 3 \cdot 2^{r-2}$ define the distance relationship graph $G_{p_n(U)}$ on $p_n(U)$ so that there is an edge between a pair of vertices when their distance is strictly less than 2^{r-2} . Recall that the distances between related pairs have dropped strictly below 2^{r-2} since $n < 3 \cdot 2^{r-2}$. Table 2 indicates that the distance between a pair of the form $\{p_{2^{r-1}}(V_0), p_{2^{r-1}}(V_i)\}$ for $2 \leq i \leq r - 2$ is $2^{r-2} - 1$ in $Q_{2^{r-1}}$. However, V_0 and V_i differ in their $(2^{r-1} + 1)^{st}$ coordinate. Thus the distance between their projections in Q_n is at least 2^{r-2} . From Table 2 we see that the only other non-related pairs of vertices that might have distance smaller than 2^{r-2} in Q_n are the pairs $\{p_n(X_i), p_n(X_j)\}$ where $1 \leq i \leq j - 2 \leq r - 4$ and the pairs $\{p_n(V_r), p_n(X_i)\}$ where $1 \leq i \leq r - 2$. Thus we see that in $G_{p_n(U)}$, $p_n(V_0)$ still has degree zero, $p_n(V_1)$ and $p_n(V_{r-1})$ still have degree one, and $p_n(V_i)$ with $2 \leq i \leq r - 2$ still have degree two. Further $p_n(X_i)$ with $1 \leq i \leq r - 2$ still have degree greater than two. However, the degree of $p_n(V_r)$ varies depending on the value of n .

If the degree of $p_n(V_r)$ in $G_{p_n(U)}$ is greater than zero, then $p_n(V_0)$ is the only vertex of degree zero and is thus distinguished.

Suppose the degree of $p_n(V_r)$ in $G_{p_n(U)}$ is zero. Then $p_n(V_0)$ and $p_n(V_r)$ are the only vertices of degree zero in $G_{p_n(U)}$. Thus any automorphism that preserves $p_n(U)$ either fixes them both or transposes them. However, the argument given in Case 1 shows that when $2^{r-1} < n < 2^r$, we can distinguish $p_n(V_0)$ and $p_n(V_r)$ by the distances they attain.

Thus in either case, $p_n(V_0)$ is distinguished and we can use the arguments of Case 1 to distinguish the remaining vertices of $p_n(U)$.

Thus we have found a 1-distinguishable determining set, *i.e.* a distinguishing class, of size $2r - 1 = 2\lceil \log_2 n \rceil - 1$ for Q_n . □

Corollary 7. For $n \geq 5$, $\lceil \log_2 n \rceil + 1 \leq \rho(Q_n) \leq 2\lceil \log_2 n \rceil - 1$.

Proof. By the remarks following Theorem 2, every distinguishing class for Q_n , $n \geq 4$, is also a determining set. By [5] a smallest such set for Q_n has size $\lceil \log_2 n \rceil + 1$. This provides the lower bound. □

The only 2-distinguishable case for Q_n that is not covered in Theorem 6 is Q_4 . The proof technique fails in this case because the given set U has no X_i when $n < 5$. If the results of Theorem 6 held for Q_4 , it would have a distinguishing class of size three. Since three is also the determining number for Q_n , such a distinguishing class would also be a minimum size determining set. It is not hard to show that there is a single isomorphism class of minimum size determining sets for Q_4 , and that one of its members, $U = \{0000, 1010, 1100\}$, has a

nontrivial set stabilizer. Thus every minimum size determining set for Q_4 has a nontrivial stabilizer and therefore cannot be a distinguishing class.

Thus the result of Theorem 6 does not hold for $n < 5$.

4 Open Questions

Question 8. For $n \geq 5$ is there a distinguishing class for Q_n that is smaller than $2^{\lceil \log_2 n \rceil} - 1$?

Question 9. For $n \geq 5$ we saw that $\rho(Q_n)$ is no bigger than a constant multiple of $\text{Det}(Q_n)$. That is, $\rho(Q_n) = O(\text{Det}(Q_n))$ in this case. For what other infinite families of graphs is this true?

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